

## Station keeping

Since Earth is an ellipsoid, the gravitational potential  $\Phi$  around Earth cannot be exactly modelled by that of a point mass. Gravitational potential of Earth is more accurately given by (in spherical coordinates)

$$\Phi(R, \phi, \lambda) \approx -\frac{\mu}{R} \left( 1 + \frac{J_2}{2} \left[ \frac{3 \sin^2(\hat{\phi}) - 1}{2} \right] \right)$$

where  $J_2 \approx 0.00108$ . These corrections induce periodic and secular perturbations to Keplerian model.

## Secular perturbations

The secular perturbation induced by the  $J_2$  term changes the longitude of node and the argument of periapsis over time and affects how mean motion changes (which grows at a constant rate in Keplerian model). In particular,

$$\dot{\Omega} = -kn \cos(i)$$

$$\dot{\omega} = kn \left( 2 - \frac{5}{2} \sin^2(i) \right)$$

$$\dot{M} = n + kn\sqrt{1 - e^2},$$

where  $n$  is the mean motion,

$$k = -\frac{3}{2} \frac{J_2 R_e^2}{a^2 (1 - e^2)},$$

and  $R_e$  is the equatorial radius of the Earth.

## Launching

Due to the rotation of Earth, if we launch a spacecraft at latitude  $\phi$ , the spacecraft is already moving at a speed  $v = \frac{\omega_e R_e \cos \phi}{\sqrt{1 - \tilde{e}^2 \sin^2 \phi}}$ .

We consider a new coordinate system called the FGH system, whose origin initially (i.e. at launch time) is at the launch site, with its  $I^1$  axis is aligned with the launch azimuth, moving at the same velocity as the launch site, which in local ENU coordinates is

$$\vec{v} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \omega_e \underbrace{\frac{R_e \cos \phi}{\sqrt{1 - \tilde{e}^2 \sin^2 \phi}}}_{\hat{R}}.$$

The FGH coordinate system is an inertial reference frame. During launch, the trajectory of the spacecraft lies in the  $I^1$ - $I^3$  plane ( $x$ - $z$  plane).

# Launching

Denote the launch time by  $t_e$ .

At launch time  $t_e$  we have  $\vec{R}^{\text{FGH}}(t_e) = G_3^{\frac{\pi}{2}-\alpha} \vec{R}^{\text{ENU}}(t_e)$ .

At time  $t$ ,

$$\vec{R}^{\text{ENU}}(t) = (\vec{G}_3^{\frac{\pi}{2}-\alpha})^\top \vec{R}^{\text{FGH}}(t) + \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \frac{\omega_e R_e \cos \phi}{\sqrt{1 - \tilde{e}^2 \sin^2 \phi}} (t - t_e)$$

$$\vec{v}^{\text{ENU}}(t) = (\vec{G}_3^{\frac{\pi}{2}-\alpha})^\top \vec{v}^{\text{FGH}}(t) + \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \frac{\omega_e R_e \cos \phi}{\sqrt{1 - \tilde{e}^2 \sin^2 \phi}}.$$